CLAIMS:

What is claimed is:

- 1 1. A system for mitigating an effect of an inoperable
- 2 servo reader on a tape drive, comprising:
- a read and write head assembly, said read and write
- 4 head assembly including a plurality of servo read
- 5 elements, wherein at least one servo read element of said
- 6 plurality of servo read elements is inoperable;
- 7 a tape, said tape including a plurality of servo
- 8 tracks; and
- 9 a track following servo system, said track following
- 10 servo system coupled to said plurality of servo read
- 11 elements, and operable to:
- 12 collect tape distortion information associated with
- 13 said tape;
- derive a track following offset value associated
- 15 with said tape distortion information; and
- 16 position at least one operable servo read element of
- 17 said plurality of servo read elements proximal to at
- 18 least one servo track of said plurality of servo tracks
- 19 and with said track following offset value applied.
 - 1 2. The system of Claim 1, wherein said plurality of
 - 2 servo read elements comprises two servo read elements.
 - 1 3. The system of Claim 1, wherein said tape distortion
 - 2 information comprises a value N, and said track following
 - 3 offset value comprises N/2.

- 1 4. The system of Claim 1, wherein said tape distortion
- 2 information comprises position error signal (PES) data.
- 1 5. The system of Claim 1, wherein said tape distortion
- 2 information comprises position error signal (PES) data
- 3 from at least one servo track of said plurality of servo
- 4 tracks.
- 1 6. The system of Claim 1, wherein said tape distortion
- 2 information comprises position error signal (PES) data
- 3 from separate servo readers of said plurality of servo
- 4 readers to produce a composite PES value.
- 1 7. The system of Claim 1, further comprising at least a
- 2 second read and write head assembly, said second read and
- 3 write head assembly including a second plurality of servo
- 4 read elements, wherein said second read and write head
- 5 assembly is operable to collect said tape distortion
- 6 information associated with said tape.
- 1 8. The system of Claim 1, wherein said plurality of
- 2 servo read elements comprises a plurality of bumps, and
- 3 one bump of said plurality of bumps includes said at
- 4 least one inoperable servo read element.
- 1 9. The system of Claim 1, wherein at least one servo
- 2 track of said plurality of servo tracks comprises at
- 3 least one of a magnetic track and an optical track.

- 1 10. A method for mitigating an effect of an inoperable
- 2 servo reader on a tape drive, the method comprising the
- 3 steps of:
- 4 collecting tape distortion information associated
- 5 with a tape;
- 6 deriving a track following offset value associated
- 7 with said tape distortion information; and
- 8 positioning at least one operable servo read element
- 9 of a plurality of servo read elements proximal to at
- 10 least one servo track of a plurality of servo tracks and
- 11 with said track following offset value applied.
- 1 11. The method of Claim 10, wherein said plurality of
- 2 servo read elements comprises two servo read elements.
- 1 12. The method of Claim 10, wherein said tape distortion
- 2 information comprises a value N, and said track following
- 3 offset value comprises N/2.
- 1 13. The method of Claim 10, wherein said tape distortion
- 2 information comprises position error signal (PES) data.
- 1 14. The method of Claim 10, wherein said tape distortion
- 2 information comprises position error signal (PES) data
- 3 from at least one servo track of said plurality of servo
- 4 tracks.
- 1 15. The method of Claim 10, wherein said tape distortion
- 2 information comprises position error signal (PES) data

- 3 from separate servo readers of said plurality of servo
- 4 readers to produce a composite PES value.
- 1 16. A computer program product in a computer readable
- 2 medium for use in a data processing system, for
- 3 mitigating an effect of an inoperable servo reader on a
- 4 tape drive, the computer program product comprising:
- 5 instructions for collecting tape distortion
- 6 information associated with a tape;
- 7 instructions for deriving a track following offset
- 8 value associated with said tape distortion information;
- 9 and
- instructions for positioning at least one operable
- 11 servo read element of a plurality of servo read elements
- 12 proximal to at least one servo track of a plurality of
- 13 servo tracks and with said track following offset value
- 14 applied.
 - 1 17. The computer program product of Claim 16, wherein
 - 2 said plurality of servo read elements comprises two servo
 - 3 read elements.
 - 1 18. The computer program product of Claim 16, wherein
 - 2 said tape distortion information comprises a value N, and
 - 3 said track following offset value comprises N/2.
 - 1 19. The computer program product of Claim 16, wherein
 - 2 said tape distortion information comprises position error
 - 3 signal (PES) data.

- 1 20. The computer program product of Claim 16, wherein
- 2 said tape distortion information comprises position error
- 3 signal (PES) data from at least one servo track of said
- 4 plurality of servo tracks.